

SVD-AE: Simple Autoencoders for Collaborative Filtering



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Motivation: Achieving Optimal Balance in Recommendation Systems

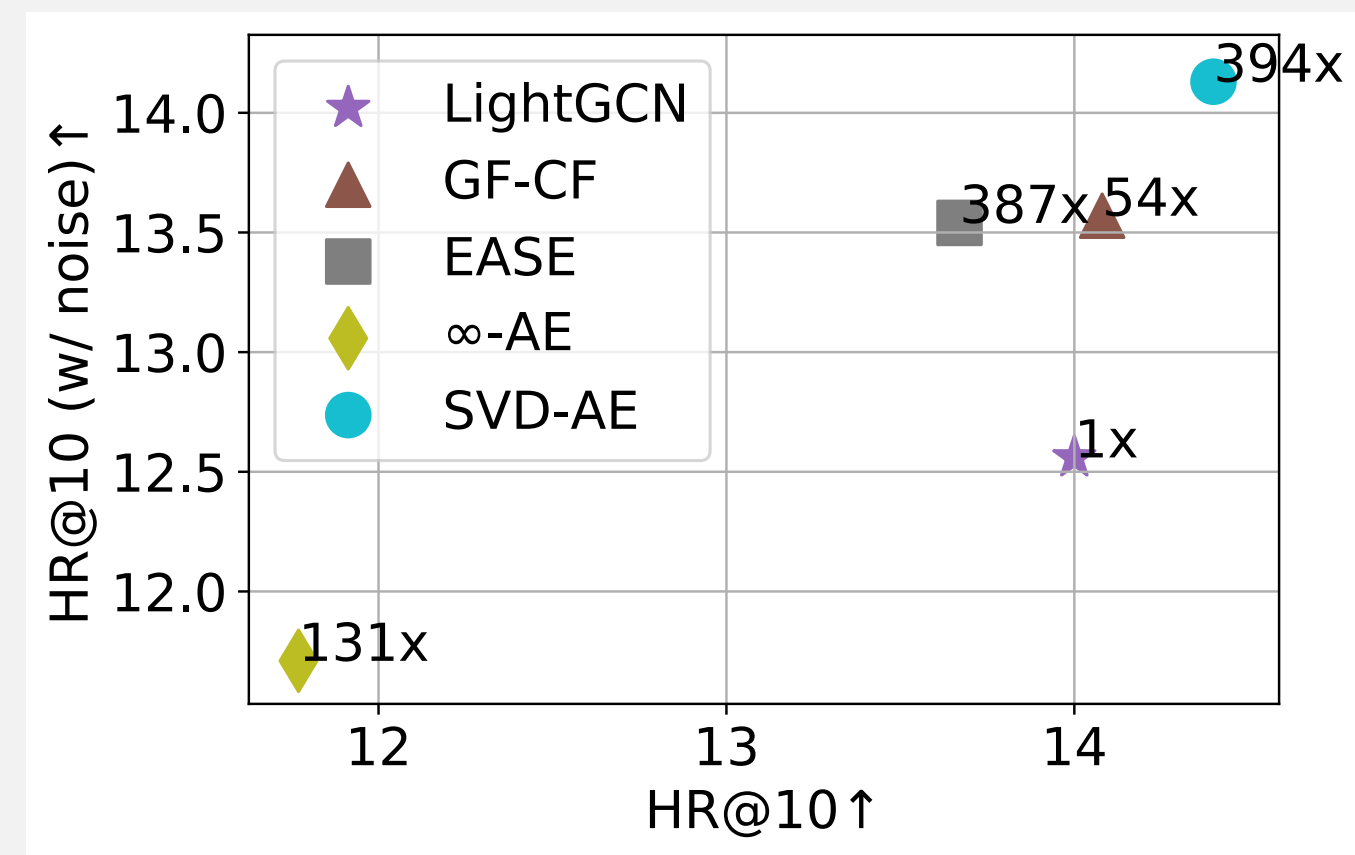
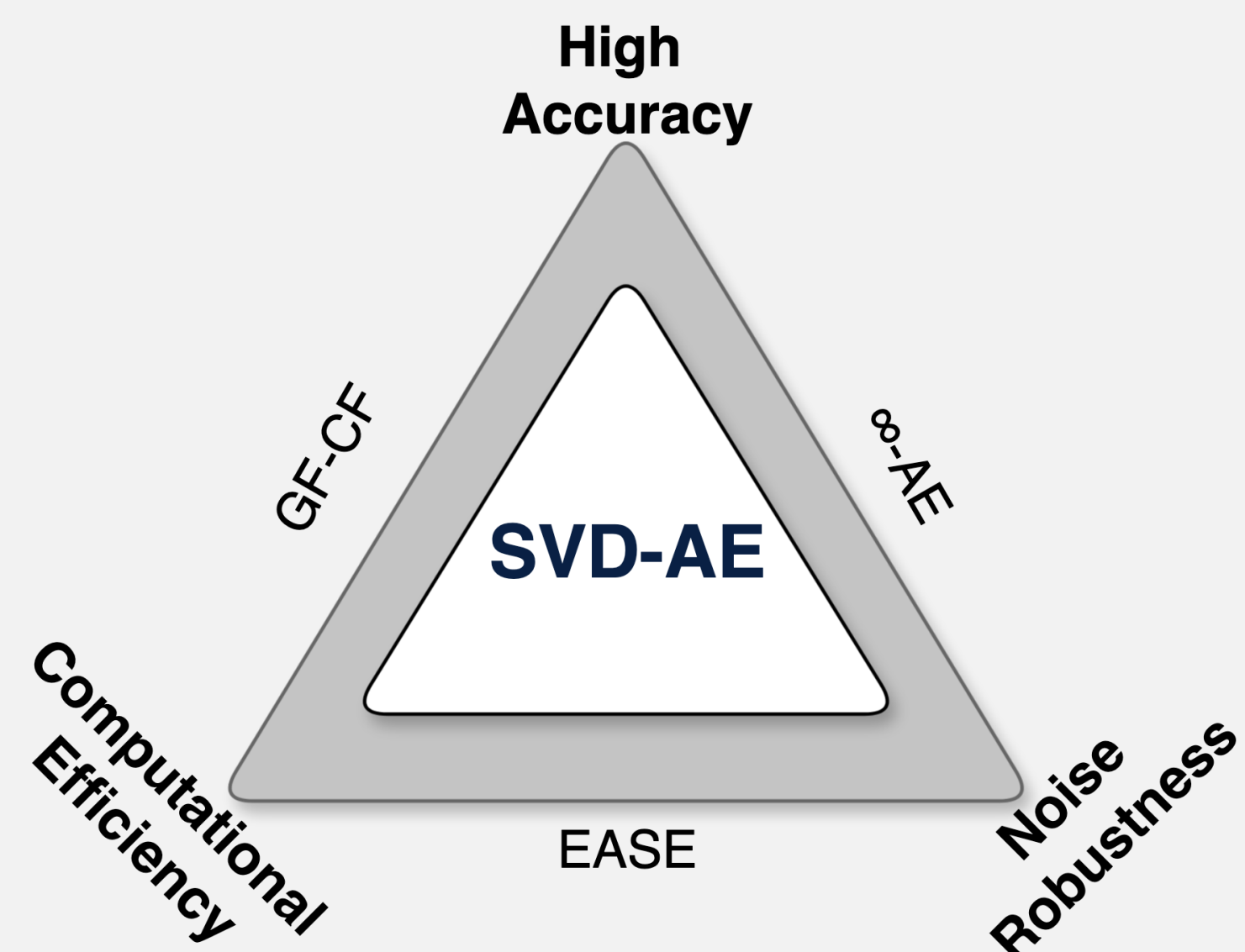


Figure 2: The accuracy, robustness, and computation time of various methods on Gowalla.

Figure 1: The best overall balance between 3 goals.

	GF-CF [1]	EASE [2]	∞-AE [3]	SVD-AE
Closed-form Solution	✓	✓	✓	✓
Autoencoder-based	✗	✓	✓	✓
Using SVD	✓	✗	✗	✓
Using Neural Networks	✗	✗	✓	✗

Table 1: Comparison of existing lightweight methods and our SVD-AE.

Performance Comparison

Dataset	Measure	LightGCN	GF-CF	MultVAE	EASE	∞-AE	SVD-AE
Gowalla	HR@10	14.00	14.08	11.88	13.67	11.77	14.40
	HR@100	37.40	38.84	33.56	35.74	34.20	37.34
	NDCG@10	13.77	13.50	11.30	13.15	10.84	13.94
	NDCG@100	21.04	21.25	18.11	20.08	17.97	21.15
	PSP@10	2.26	2.47	2.09	2.31	2.02	2.48
Yelp2018	HR@10	4.32	4.87	4.31	4.65	4.62	4.90
	HR@100	19.01	20.86	18.75	17.74	18.33	19.79
	NDCG@10	4.19	4.66	4.10	4.55	4.48	4.74
	NDCG@100	9.57	10.53	9.37	9.37	9.54	10.22
	PSP@10	0.39	0.44	0.43	0.42	0.43	0.45
ML-1M	HR@10	29.07	30.81	27.86	30.43	31.15	31.79
	HR@100	57.62	59.10	57.67	57.74	60.75	59.33
	NDCG@10	30.30	32.37	28.44	31.90	32.27	33.55
	NDCG@100	39.95	42.00	39.34	40.95	42.54	42.57
	PSP@10	3.01	3.17	3.13	3.16	3.22	3.22
ML-10M	HR@10	34.79	35.10	34.20	36.30	35.83	36.76
	HR@100	64.11	64.23	64.55	64.78	64.48	64.80
	NDCG@10	35.60	36.02	34.48	37.63	36.93	37.75
	NDCG@100	46.14	45.71	45.23	46.74	46.27	46.97
	PSP@10	4.69	4.73	4.82	4.76	4.74	4.93

Table 2: Performance evaluation of overall performance among SVD-AE and baselines

Generalized Linear Autoencoder for Recommender Systems

► The objective function of linear autoencoder is:

$$\min_{\mathbf{R}} \|\mathbf{R} - \hat{\mathbf{R}}\|_2^2, \quad \text{s.t. } \mathcal{C}, \quad (1)$$

- $\mathbf{R} \in \{0, 1\}^{[U] \times [I]}$ is the given user-item interaction matrix
- $\hat{\mathbf{R}} \in \{0, 1\}^{[U] \times [I]}$ is the reconstructed interaction matrix

► EASE uses ridge regression with a regularization term:

$$\min_{\mathbf{B}} \|\mathbf{R} - \mathbf{R}\mathbf{B}\|_F^2 + \lambda \cdot \|\mathbf{B}\|_F^2, \quad \text{s.t. } \text{diag}(\mathbf{B}) = 0, \quad (2)$$

► ∞-AE uses Kernelized Ridge Regression:

$$\text{argmin}_{\{\alpha_j\}_{j=1}^{|I|}} \sum_{u \in U} \|\mathbf{R}_u - f(\mathbf{R}_u | \alpha)\|_2^2 + \lambda \cdot \|f\|_{\mathcal{H}}^2. \quad (3)$$

► Closed-form solutions for optimal $\hat{\mathbf{R}}$ in different methods:

$$\hat{\mathbf{R}} = \begin{cases} \mathbf{R} \cdot (\mathbf{I} - \hat{\mathbf{P}} \cdot \text{diagMat}(\hat{\mathbf{I}} \oslash \text{diag}(\hat{\mathbf{P}}))) & (\text{EASE}), \\ \mathbf{K} \cdot (\mathbf{K} + \lambda \mathbf{I})^{-1} \cdot \mathbf{R} & (\infty\text{-AE}), \\ \tilde{\mathbf{R}} \cdot \mathbf{V} \tilde{\Sigma}^+ \mathbf{Q}^T \mathbf{R} & (\text{SVD-AE}), \end{cases} \quad (4)$$

► $\hat{\mathbf{P}} = (\mathbf{R}^T \mathbf{R} + \lambda \mathbf{I})^{-1}$.

► $\tilde{\mathbf{R}} = \mathbf{D}_U^{-\frac{1}{2}} \mathbf{R} \mathbf{D}_I^{-\frac{1}{2}}$ is a normalized adjacency matrix.

The Presence of Noise

- \mathbf{R} often contains noisy interactions that don't reflect true user preferences.
- EASE and ∞-AE use λ to prevent overfitting to noisy rating matrix.
- Smaller λ minimizes MSE but doesn't guarantee better performance.

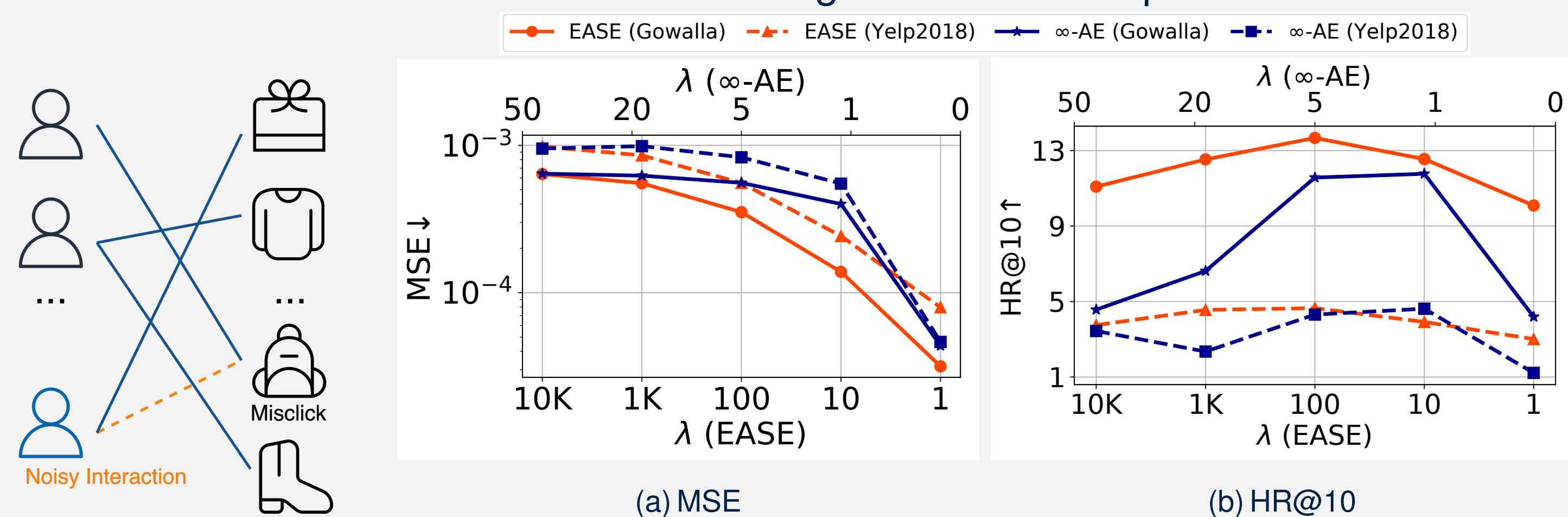


Figure 3: The performance comparison with different regularization parameters.

Efficiency Comparison

Model	ML-1M		ML-10M	
	Pre-processing	Training	Pre-processing	Training
LightGCN	N/A	2.44h	N/A	132.97h
GF-CF	4.62s	6.37s	28.98s	1260.80s
EASE	4.52s	5.72s	52.63s	6.05s
∞-AE	N/A	2.24s	N/A	388.39s
SVD-AE	0.54s	2.06s	47.59s	3.06s

Table 3: Efficiency comparison on overall computation time.

Robustness on Noise

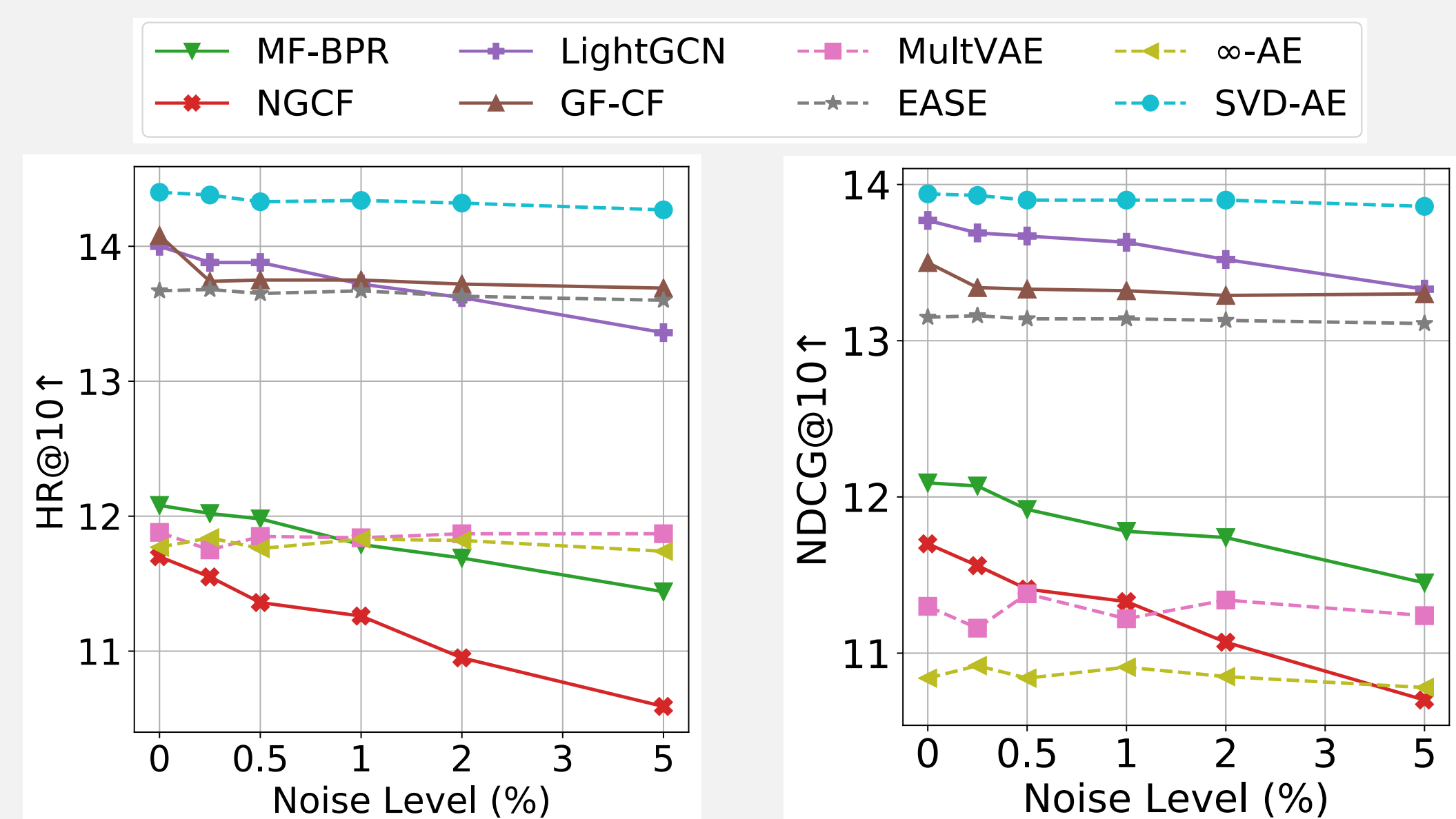


Figure 4: Robustness evaluation against noise level.

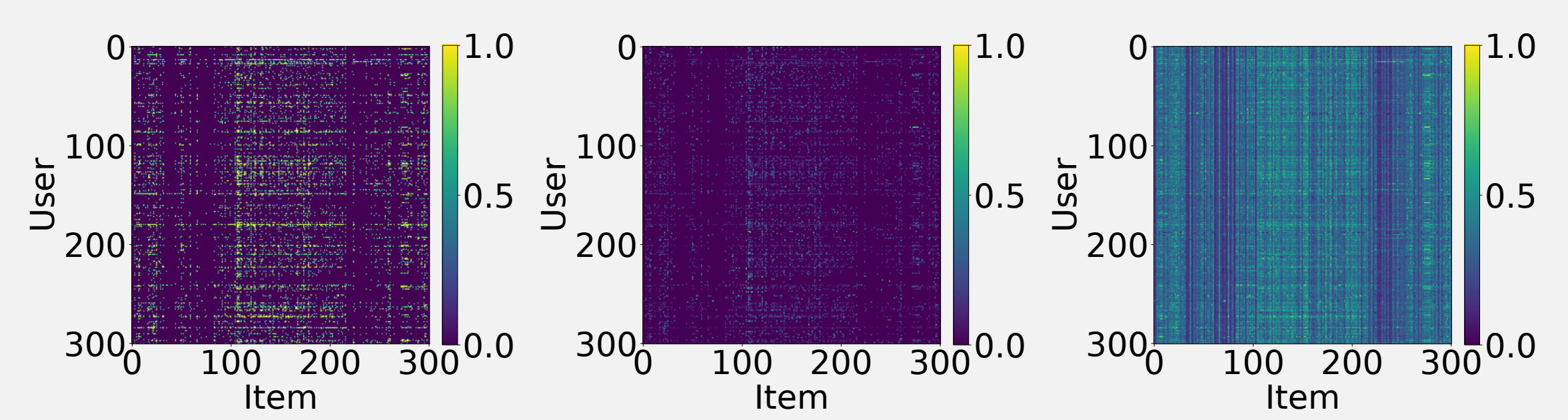


Figure 5: The smoothing effect of the truncated SVD in reducing noise.

SVD-AE Method

► SVD-AE solves a ridge regression-like problem:

$$\min_{\mathbf{B}} \|\mathbf{R} - \tilde{\mathbf{R}}\mathbf{B}\|_2^2 \quad (5)$$

► The regularization term is implicitly handled by truncated SVD.

► Novel closed-form solution:

$$\mathbf{B} = \tilde{\mathbf{R}}^+ \mathbf{R} = \mathbf{V} \tilde{\Sigma}^+ \mathbf{Q}^T \mathbf{R}, \quad (6)$$

► Let $\tilde{\mathbf{R}} = \mathbf{Q} \tilde{\Sigma} \mathbf{V}^T$ be the SVD of $\tilde{\mathbf{R}}$, then we can get the pseudo-inverse of $\tilde{\mathbf{R}}$, $\tilde{\mathbf{R}}^+$.

► $\mathbf{Q} \in \mathbb{R}^{[U] \times m}$ and $\mathbf{V} \in \mathbb{R}^{[I] \times m}$ are top- m singular vectors

► $\tilde{\Sigma}^+$ contains inverse of top- m singular values of $\tilde{\mathbf{R}}$

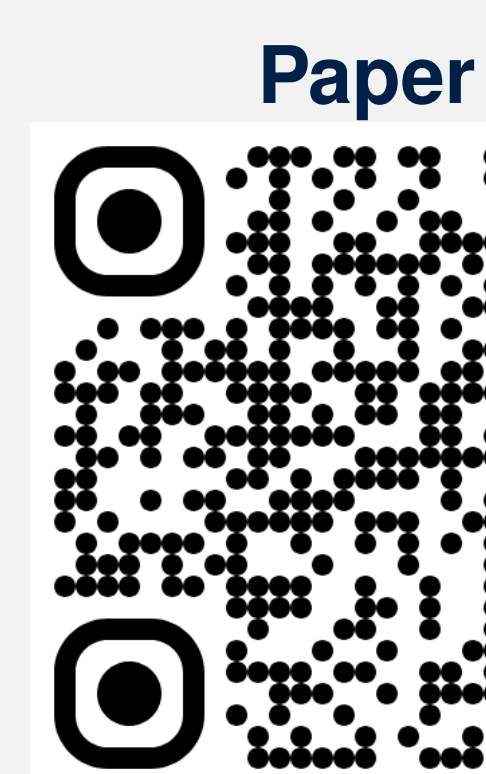
► $m = \lfloor \gamma \times \min(|U|, |I|) \rfloor$, where $\gamma = 0.04$ is optimal for all datasets

► Low-rank Inductive Bias in SVD-AE:

- Reduces noise (smaller singular values).
- Speeds up calculations for large, sparse matrices.

References

- [1] Yifei Shen, Yongji Wu, Yao Zhang, Caihua Shan, Jun Zhang, B Khaled Letaief, and Dongsheng Li. How powerful is graph convolution for recommendation? In *CIKM*, 2021.
- [2] Harald Steck. Embarrassingly shallow autoencoders for sparse data. In *TheWebConf*, 2019.
- [3] Naveen Sachdeva, Mehak Preet Dhaliwal, Carole-Jean Wu, and Julian McAuley. Infinite recommendation networks: A data-centric approach. In *NeurIPS*, 2022.



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